

Resource-Efficient, Hierarchical Auto-tuning of a Hybrid Lattice Boltzmann Computation on the Cray XT4

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Background



Arithmetic Intensity

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***** True Arithmetic Intensity (AI) ~ Total Flops / Total DRAM Bytes

- Some HPC kernels have an arithmetic intensity that scales with problem size (increased temporal locality), but remains constant on others
- Arithmetic intensity is ultimately limited by compulsory traffic
- Arithmetic intensity is diminished by conflict or capacity misses.



Kernel Arithmetic Intensity and Architecture

- For a given architecture, one may calculate its flop:byte ratio.
- ✤ For a 2.3GHz Quad Core Opteron (like in the XT4),
 - I SIMD add + 1 SIMD multiply per cycle per core
 - 12.8GB/s of DRAM bandwidth
 - = 36.8 / 12.8 ~ 2.9 flops per byte
- When a kernel's arithmetic intensity is substantially less than the architecture's flop:byte ratio, transferring data will take longer than computing on it

→ memory-bound

- When a kernel's arithmetic intensity is substantially greater than the architecture's flop:byte ratio, computation will take longer than data transfers
 - → compute-bound





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LBMHD

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- Plasma turbulence simulation via Lattice Boltzmann Method
- Two distributions:
 - momentum distribution (27 scalar components)
 - magnetic distribution (15 vector components)
- Three macroscopic quantities:
 - Density
 - Momentum (vector)
 - Magnetic Field (vector)









- Code Structure
 - time evolution through a series of collision() and stream() functions
- When parallelized, stream() should constitute 10% of the runtime.
- collision()'s Arithmetic Intensity:
 - Must read 73 doubles, and update 79 doubles per lattice update (1216 bytes)
 - Requires about 1300 floating point operations per lattice update
 - Just over 1.0 flops/byte (ideal architecture)
 - Suggests LBMHD is **memory-bound** on the XT4.
- Structure-of-arrays layout (component's are separated) ensures that cache capacity requirements are independent of problem size
- However, TLB capacity requirement increases to >150 entries
- periodic boundary conditions



Previous Work: Auto-tuning LBMHD on Multicore SMPs

Samuel Williams, Jonathan Carter, Leonid Oliker, John Shalf, Katherine Yelick, "Lattice Boltzmann Simulation Optimization on Leading Multicore Platforms", International Parallel & Distributed Processing Symposium (IPDPS), 2008.

Best Paper, Application Track



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LBMHD Performance

(reference implementation)



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Generally, scalability looks

UP

Scalability is good

G

E S R Ο

but is performance good?

*collision() only



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- For a given lattice update, the requisite velocities can be mapped to a relatively narrow range of cache sets (lines).
- As one streams through the grid, one cannot fully exploit the capacity of the cache as conflict misses evict entire lines.
- In an structure-of-arrays format, pad each component such that when referenced with the relevant offsets (±x,±y,±z) they are uniformly distributed throughout the sets of the cache
- Maximizes cache utilization and minimizes conflict misses.



LBMHD Performance

(lattice-aware array padding)

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- LBMHD touches >150 arrays.
- Most caches have limited associativity
- Conflict misses are likely
- Apply **heuristic** to pad arrays



Vectorization

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- Two phases with a lattice method's collision() operator:
 - reconstruction of macroscopic variables
 - updating discretized velocities
- Normally this is done one point at a time.
- Change to do a vector's worth at a time (loop interchange + tuning)





LBMHD Performance

(architecture specific optimizations)





- Add unrolling and reordering of inner loop
- Additionally, it exploits SIMD where the compiler doesn't
- Include a SPE/Local Store optimized version





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Limitations

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- Ignored MPP (distributed) world
- Kept problem size fixed and cubical
- When run with only 1 process per SMP, maximizing threads per process always looked best



Hybrid MPI+Pthreads Implementations

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Flat MPI

R R U P E. U - F E. С H E. S G 0 U T. N 0

- In the flat MPI world, there is one process per core, and only one thread per process
- All communication is through MPI





Hybrid MPI

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- As multicore processors already provide cache coherency for free, we can exploit it to reduce MPI overhead and traffic.
- We use pthreads for threading (other possibilities exist)
- For correctness, we are required to include a intra-process (thread) barrier between function calls for correctness.

(we wrote our own)

- We can choose any balance between processes/ node and threads/process (we explored powers of 2)
- We did not assume a thread-safe MPI implementation. As such, only thread 0 performs MPI calls

E	S	GRO	0	UP	
	thread 0 (core 0)	ess 0— thread 1 (core 1)		thread 0 (core 2)	thread 1 (core 3)
ba	arrier()		-	barrier()	
	collision()	collision()		collision()	collision()
bi	arrier()		_	barrier()	
	pack()	pack()	-	pack()	pack()
ba	arrier()		-	barrier()	
	MPI()		_	MPI()	
h				harrier()	
07	unpack()	unpack()		unpack()	unpack()
b	arrier()		_	barrier()	
	pack()	pack()	-	pack()	pack()
b	arrier()		-	barrier()	
	MPI()			MPI()	
h				harrier()	
0.	unpack()	unpack()	-	unpack()	unpack()
b	arrier()		_	barrier()	
	pack()	pack()	-	pack()	pack()
b	arrier()		-	barrier()	
	MPI()			MPI()	
h				harrier()	
07	unpack()	unpack()	-	unpack()	unpack()
b	arrier()		_	barrier()	



Distributed, Hybrid Auto-tuning

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The Distributed Auto-tuning Problem

- We believe that even for relatively large problems, only auto-tuning the local computation (e.g. IPDPS'08) will deliver sub-optimal MPI performance.
- We have a combinatoric explosion in the search space coupled with a large problem size (number of nodes)

at each concurrency: for all aspect ratios for all process/thread balances for all thread grids for all data structures for all coding styles (reference, vectorized, vectorized+SIMDized) for all prefetching for all vector lengths for all code unrollings/reorderings benchmark



Our Approach

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We employ a resource-efficient 3-stage greedy algorithm that successively prunes the search space:

for all data structures

for all coding styles (reference, vectorized, vectorized+SIMDized)

for all prefetching

for all vector lengths

for all code unrollings/reorderings

benchmark

at limited concurrency (single node):

for all aspect ratios

for all process/thread balances

for all thread grids

benchmark

at full concurrency:

for all process/thread balances

benchmark



Stage 1

- In stage 1, we prune the code generation space.
- We ran this as a 128^3 problem with 4 threads.
- As VL, unrolling, and reordering may be problem dependent, we only prune:
 - padding
 - coding style
 - prefetch distance
- We observe that vectorization with SIMDization, and a prefetch distance of 1 cache line worked best







- Suppose we wish to explore this color-coded optimization space.
- In the serial world (or fully threaded nodes), the tuning is easily run
- However, in the MPI or hybrid world a problem arises as processes are not guaranteed to be synchronized.
- As such, one process may execute some optimizations faster than others simply due to fortuitous scheduling with another processes' trials
- Solution: add an MPI_barrier() around each trial





Stage 2 (continued)

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We create a database of optimal VL/unrolling/DLP parameters for each thread/process balance, thread grid, and aspect ratio







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- Given the data base from Stage 2,
- we run few large problem using the best known parameters/thread grid for different thread/process balances.
- We select the parameters based on minimizing
 - overall local time
 - collision() time
 - local stream() time



Results

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XT4 Results (512³ problem on 512 cores)

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- Finally, we present the best data for progressively more aggressive auto-tuning efforts/
- Note each of the last 3 bars may have unique MPI decompositions as well as VL/unroll/DLP
- Observe that for this large problem, auto-tuning flat MPI delivered significant boosts (2.5x)
- However, expanding auto-tuning to include the domain decomposition and balance between threads and processes provided an extra 17%
- 2 processes with 2 threads was best





XT4 Results (512³ problem on 512 cores)

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- When examining the execution time breakdown, we see how the auto-tuner consistently favored faster *collision()* times.
- In the hybrid world we see a trade off between MPI time and stream() time
- As threads/process increase, we get less bandwidth, but less traffic.





Summary



- Multicore cognizant auto-tuning dramatically improves even flat MPI performance.
- Tuning the domain decomposition and hybrid implementations yielded almost an additional 20% performance boost.
- Although hybrid MPI promises improved performance through reduced communication, it is critical all components be threadparallelized.

Future work will move to other architectures (like the XT5), examine a range of problem sizes, and attempt to thread-parallelize the MPI.



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- George Vahala and his research group provided the original (FORTRAN) version of the LBMHD code.



Questions?