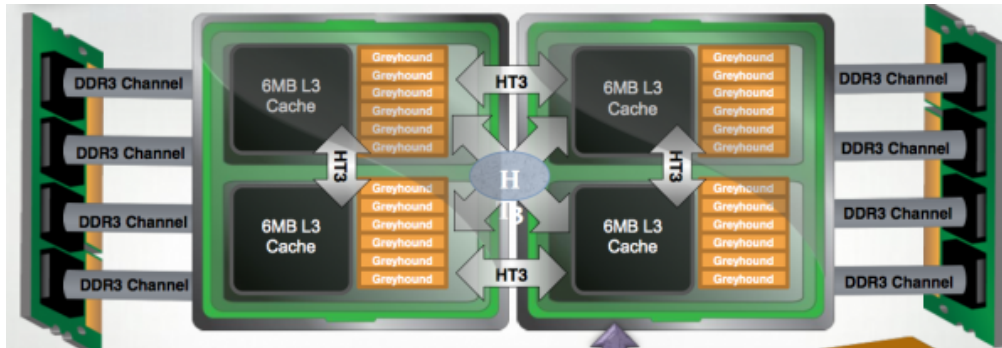


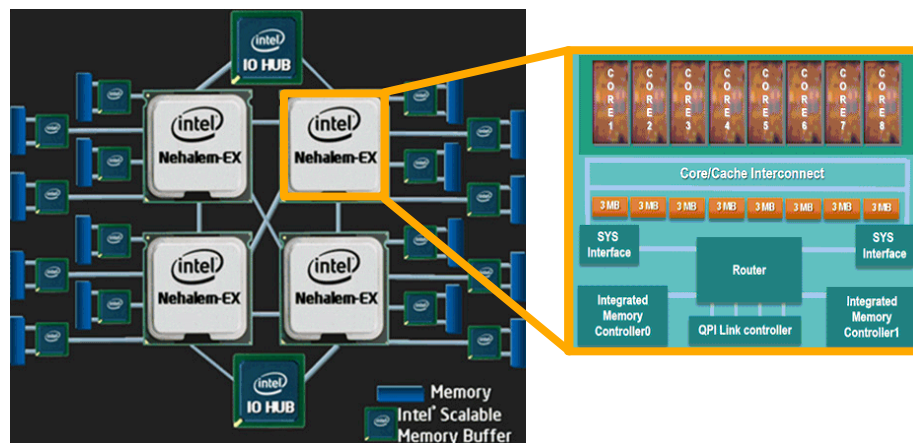
# Hierarchical Teams in a Single-Program, Multiple- Data Execution Model

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DEGAS Retreat  
June 4, 2013

- ❖ Parallel machines have hierarchical structure



Dual Socket AMD  
MagnyCours

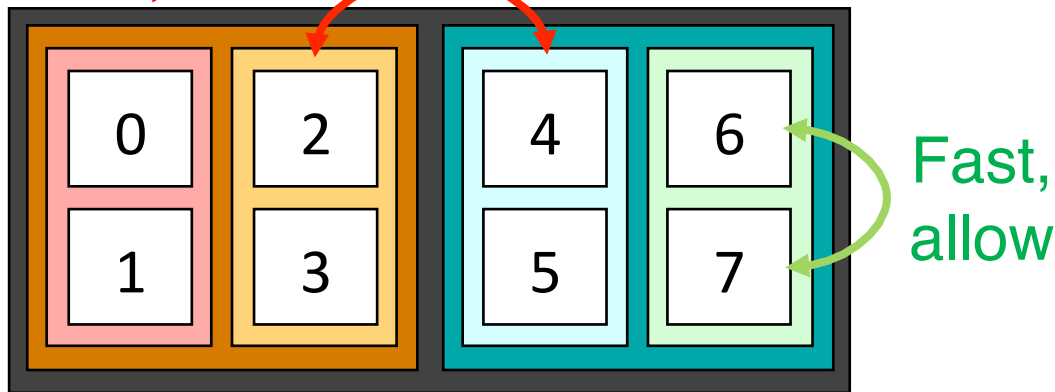


Quad Socket Intel  
Nehalem EX

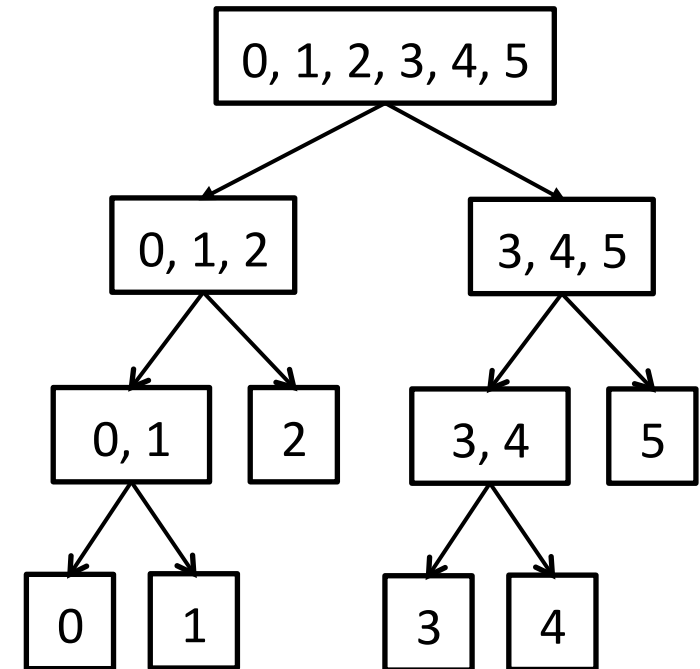
- ❖ Expect this hierarchical trend to continue with manycore

- ❖ Applications can reduce communication costs by adapting to machine hierarchy

Slow, avoid

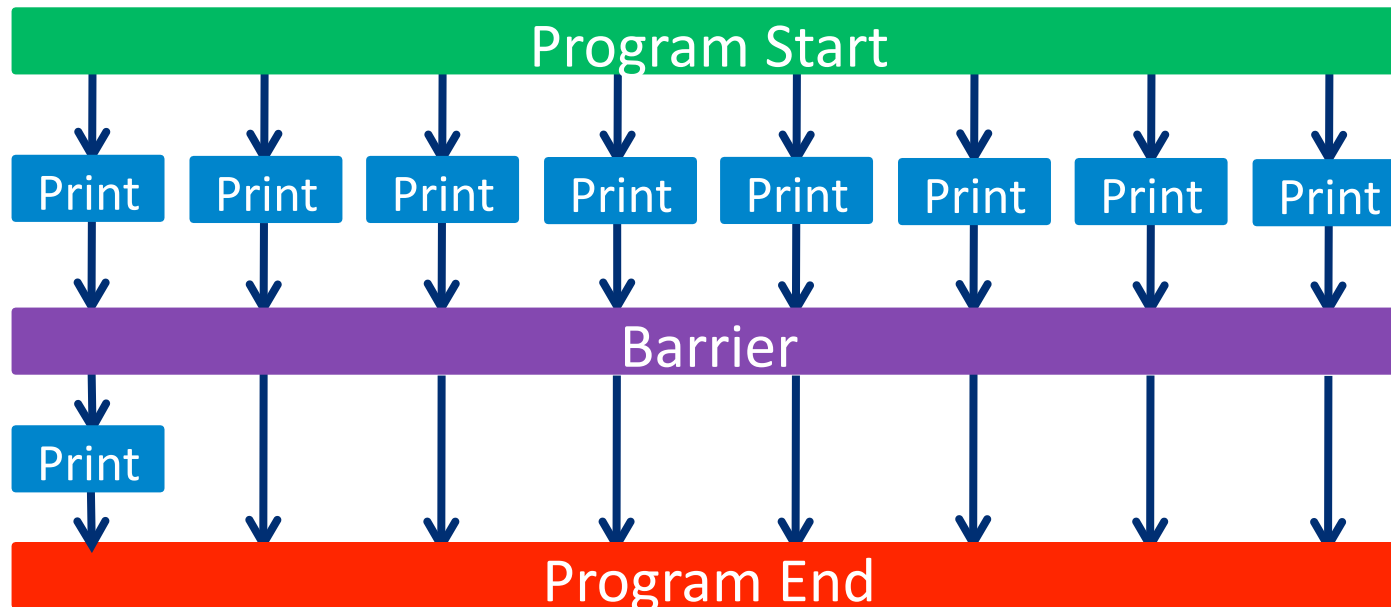


- ❖ Applications may also have inherent, algorithmic hierarchy
  - Recursive algorithms
  - Composition of multiple algorithms
  - Hierarchical division of data



- ❖ Single program, multiple data (SPMD): fixed set of threads execute the same program image

```
public static void main(String[] args) {
    System.out.println("Hello from " + Ti.thisProc());
    Ti.barrier();
    if (Ti.thisProc() == 0)
        System.out.println("Done.");
}
```



## ❖ Task parallel

```
int[] mergeSort(int[] data) {  
    int len = data.length;  
    if (len < threshold)  
        return sequentialSort(data);  
    d1 = fork mergeSort(data[0:len/2-1]);  
    d2 = mergeSort(data[len/2:len-1]);  
    join d1;  
    return merge(d1, d2);  
}
```

## ❖ Cannot fork threads in SPMD

- Must rewrite to execute over fixed set of threads

## ❖ SPMD

```

int[] mergeSort(int[] data, int[] ids) { Team
    int len = data.length;
    int threads = ids.length;
    if (threads == 1) return sequentialSort(data);
    if (myId in ids[0:threads/2-1])
        d1 = mergeSort(data[0:len/2-1],
                       ids[0:threads/2-1]);
    else
        d2 = mergeSort(data[len/2:len-1],
                       ids          threads-1]);
    barrier(ids); Team
    if (myId == ids[0]) return merge(d1, d2);
}

```

**Collective**

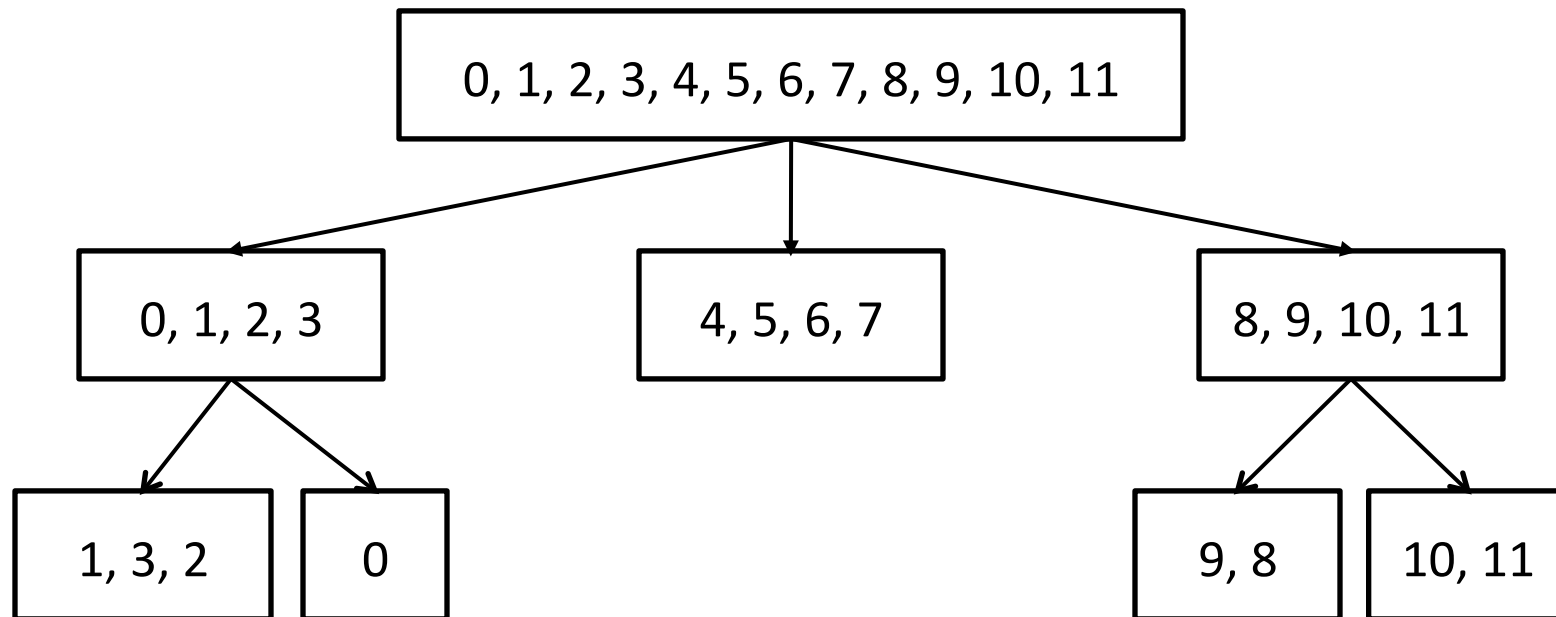
- ❖ Thread *teams* are basic units of cooperation
  - Groups of threads that cooperatively execute code
  - Collective operations over teams
- ❖ Other languages have teams
  - MPI communicators, UPC teams
- ❖ However, those teams are flat
  - Do not match hierarchical structure of algorithms, machines
  - Misuse of teams can result in deadlock

```
Team t1 = new Team(0:7);  
Team t2 = new Team(0:3);  
if (myId == 0) barrier(t1);  
else barrier(t2);
```

- ❖ Structured, hierarchical teams are the solution
  - Expressive: match structure of algorithms, machines
  - Safe: eliminate many sources of deadlock
  - Analyzable: enable simple program analysis
  - Efficient: allow users to take advantage of machine structure, resulting in performance gains

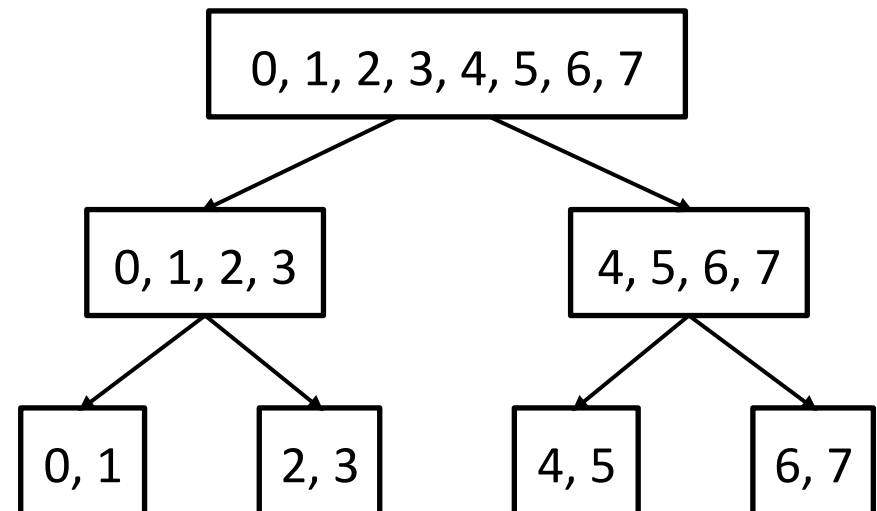
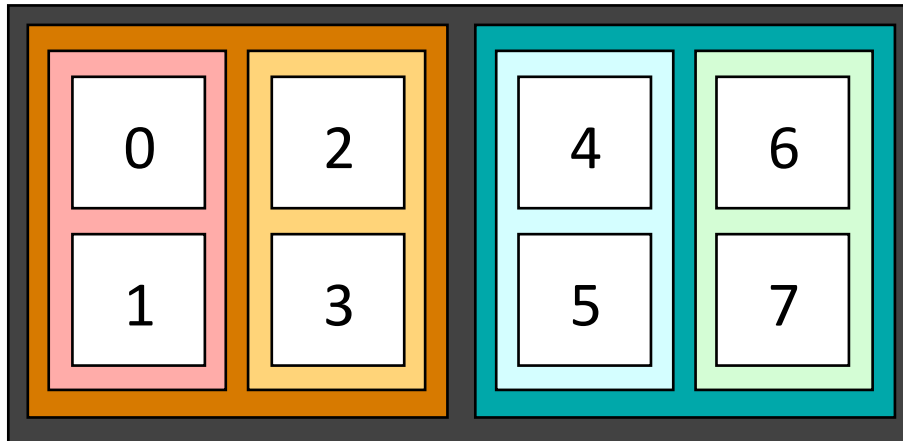


- ❖ Threads comprise teams in tree-like structure
- ❖ First-class object to allow easy creation and manipulation



- ❖ Provide mechanism for querying machine structure and thread mapping at runtime

```
Team T = Ti.defaultTeam();
```



- ❖ Thread teams may execute distinct tasks

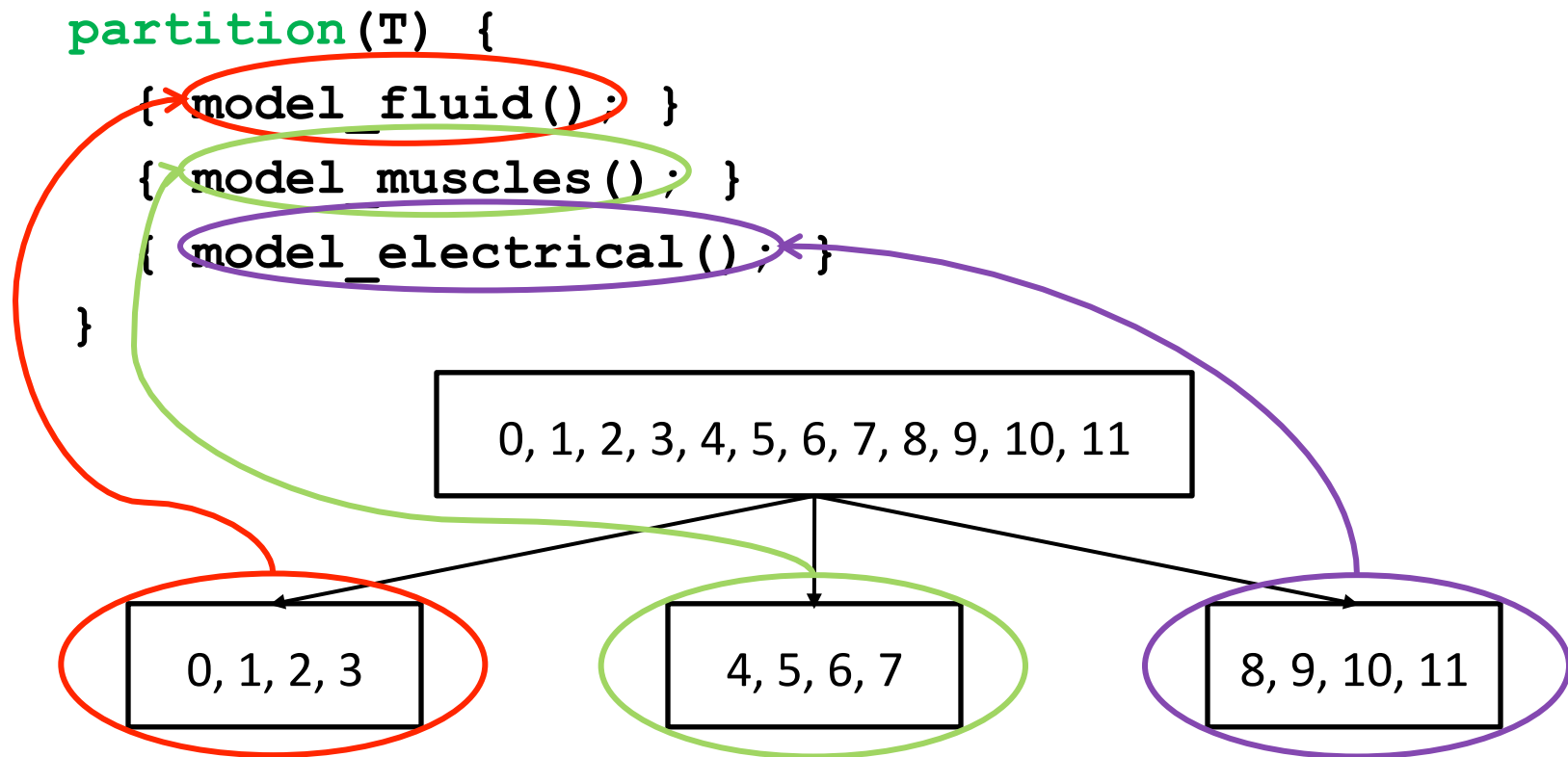
```
partition(T) {
    { model_fluid(); }
    { model_muscles(); }
    { model_electrical(); }
}
```

- ❖ Threads may execute the same code on different sets of data as part of different teams

```
teamsplit(T) {
    row_reduce();
}
```

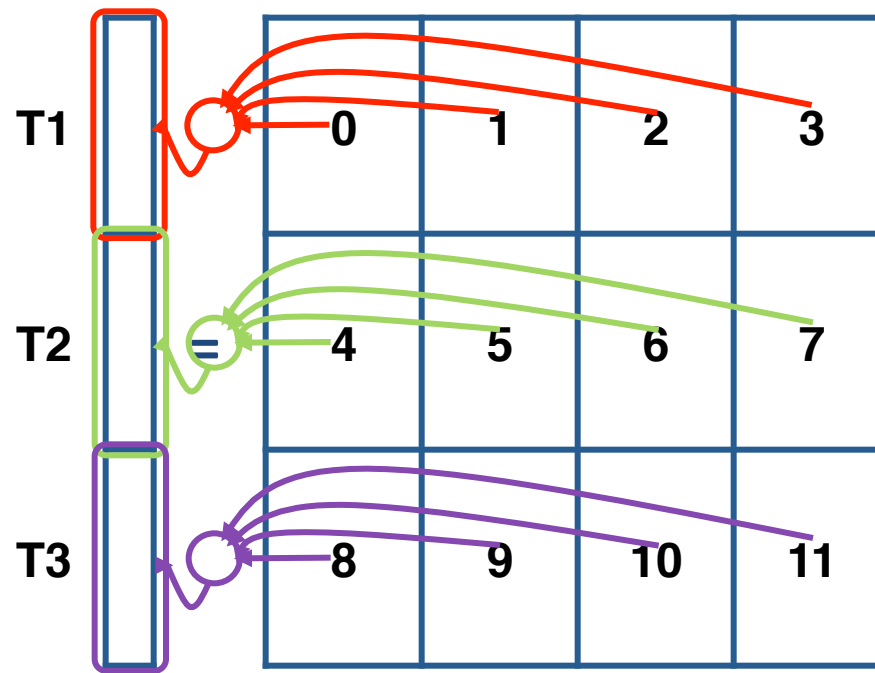
- ❖ Scoping rules prevent some types of deadlock
  - Execution team determined by enclosing construct

- ❖ Different subteams of  $\mathbb{T}$  execute each of the branches



- ❖ Each subteam of `rowTeam` executes the reduction on its own

```
teamsplit(rowTeam) {
  Reduce.add(mtmp, myResults0, rpivot);
}
```



❖ Constructs can be nested

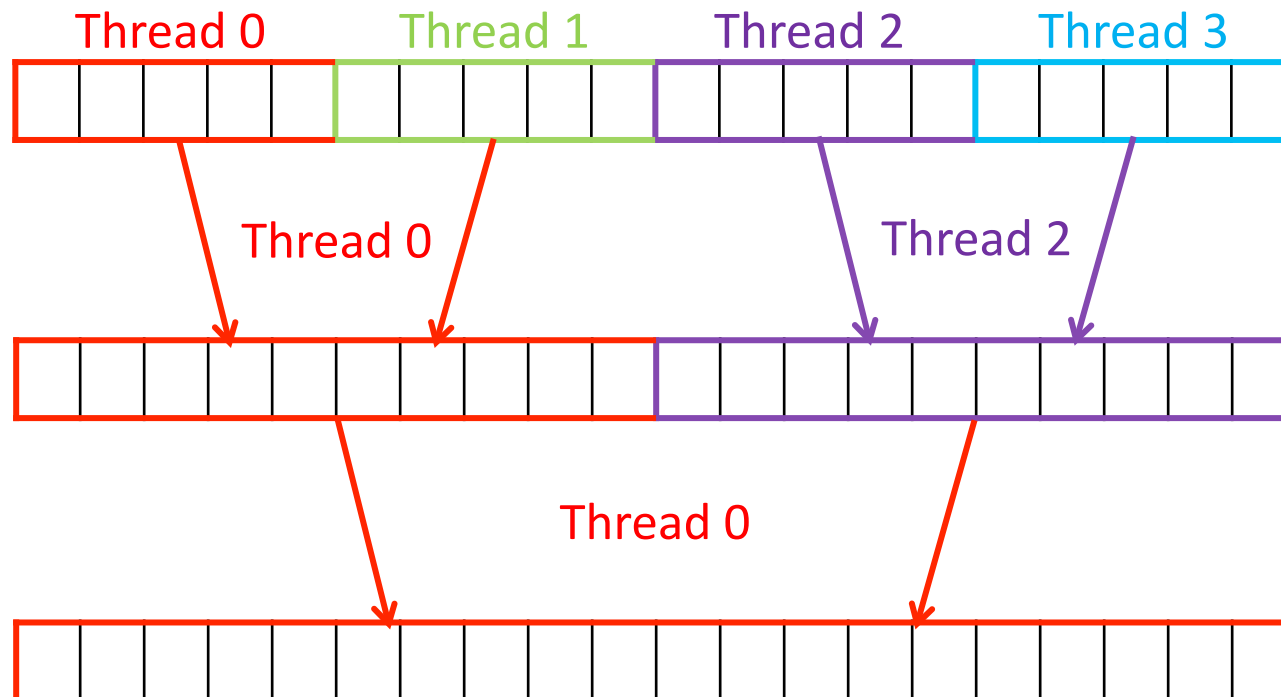
```
teamsplit(T) {
    teamsplit(T.myChildTeam()) {
        level1_work();
    }
    level2_work();
}
```

❖ Program can use multiple teams

```
teamsplit(columnTeam) {
    myOut.vbroadcast(cpivot);
}
teamsplit(rowTeam) {
    Reduce.add(mtmp, myResults0, rpivot);
}
```

- ❖ Distributed sorting application using new hierarchical constructs
  
- ❖ Three pieces: sequential, shared memory, and distributed
  - Sequential quick sort from Java 1.4 library
  - Shared memory merge sort
  - Distributed memory sample sort

- ❖ Divide elements equally among threads
  - Each thread processes its elements sequentially
- ❖ Merge in parallel
  - Number of threads halved in each iteration

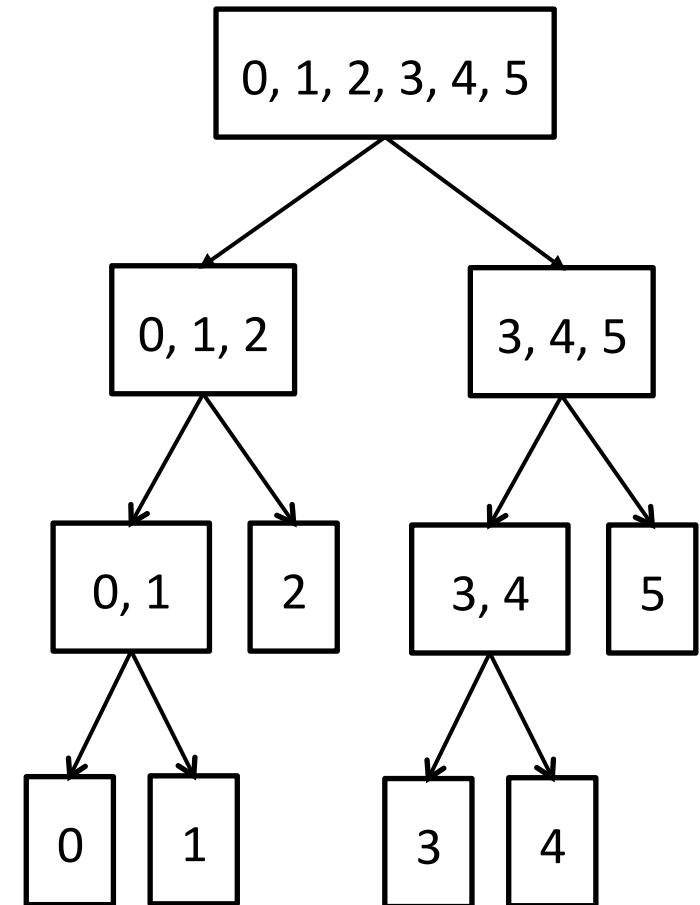




- ❖ Team hierarchy is binary tree
- ❖ Trivial construction

```
static void divideTeam(Team t) {
    if (t.size() > 1) {
        t.splitTeam(2);
        divideTeam(t.child(0));
        divideTeam(t.child(1));
    }
}
```

- ❖ Threads walk down to bottom of hierarchy, sort, then walk back up, merging along the way



## ❖ Control logic for sorting and merging

```

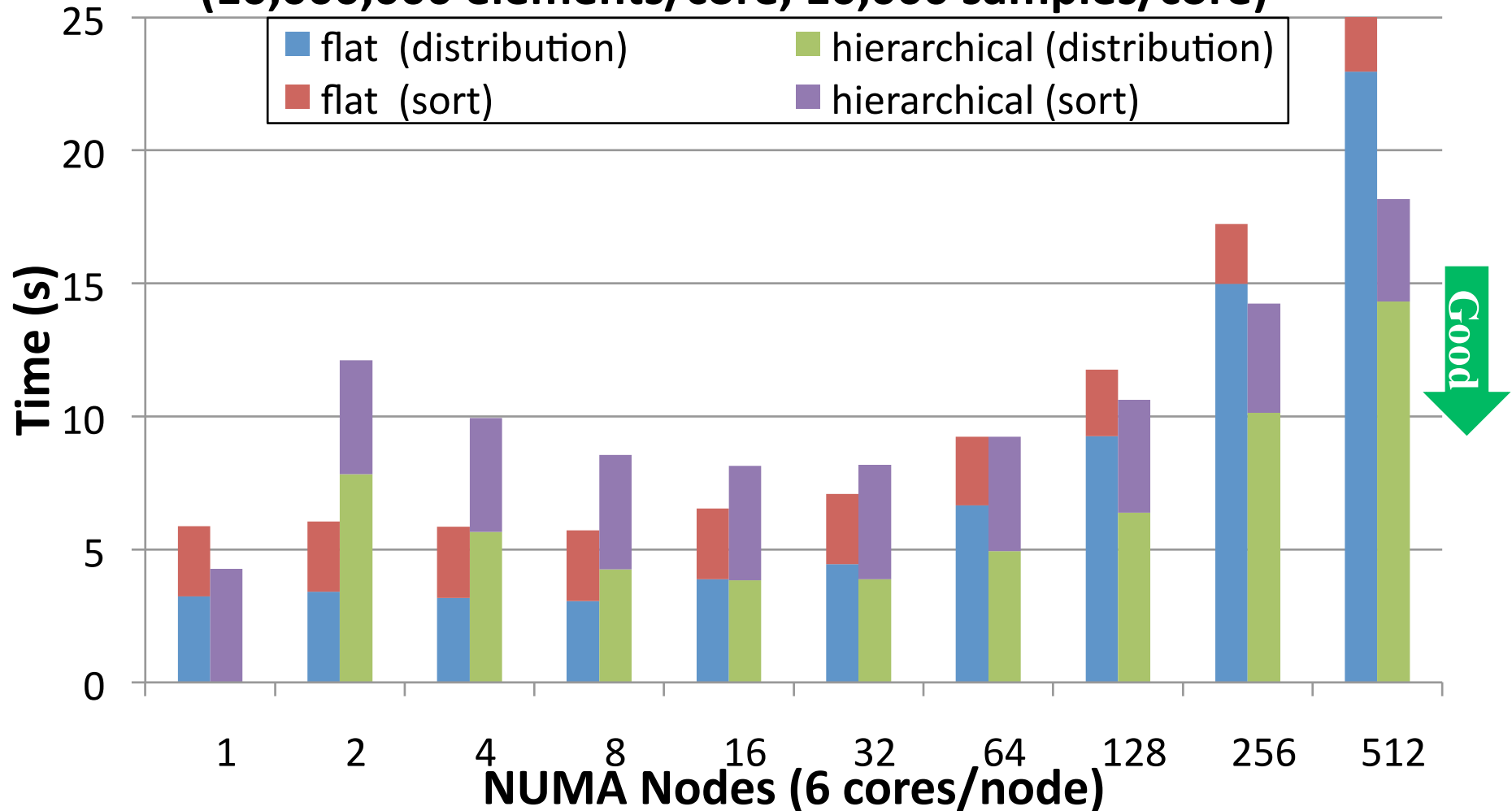
static single void sortAndMerge(Team t) {
    if (Ti.numProcs() == 1) {
        allRes[myProc] = sequentialSort(myData);
    } else {
        teamsplit(t) {
            sortAndMerge(t.myChildTeam());
        }
        Ti.barrier();
        if (Ti.thisProc() == 0) {
            int otherProc = myProc + t.child(0).size();
            int[1d] myRes = allRes[myProc];
            int[1d] otherRes = allRes[otherProc];
            int[1d] newRes = target(t.depth(), myRes, otherRes);
            allRes[myProc] = merge(myRes, otherRes, newRes);
        }
    }
}

```

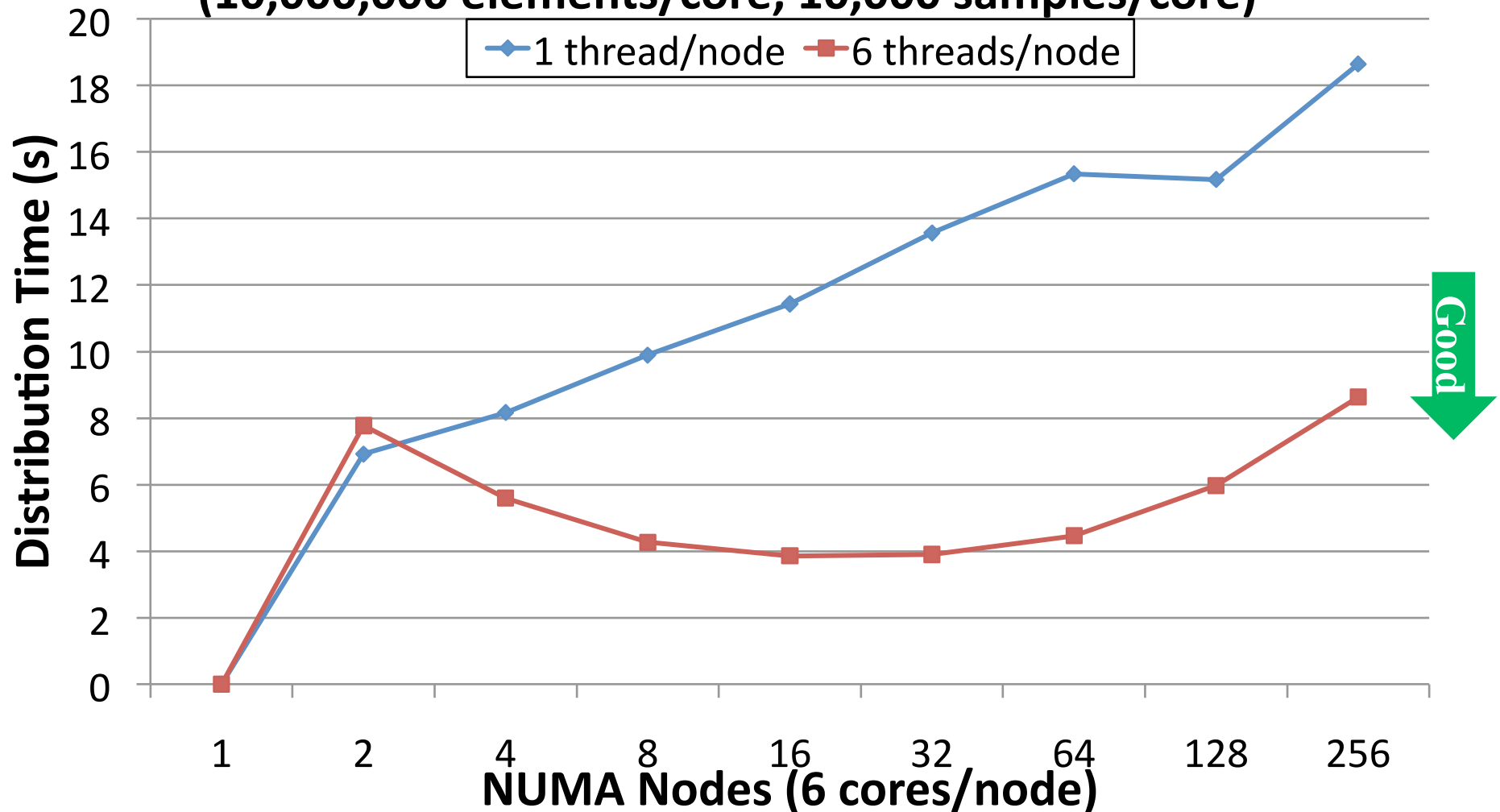
- ❖ Three strategies for hierarchical machines (e.g. clusters of SMPs):
  - Treat the machine as a flat collection of processors that don't share memory
  - Compose a distributed communication library (e.g. MPI) with a shared memory library (e.g. Pthreads)
  - Implement a hierarchical algorithm that takes advantage of both shared memory and all available concurrency
- ❖ Sort example:
  - Pure sample sort treats the machine as flat
  - Hierarchical sort uses sampling/distribution between shared-memory domains, SMP sort in a node

## Distributed Sort (Cray XE6)

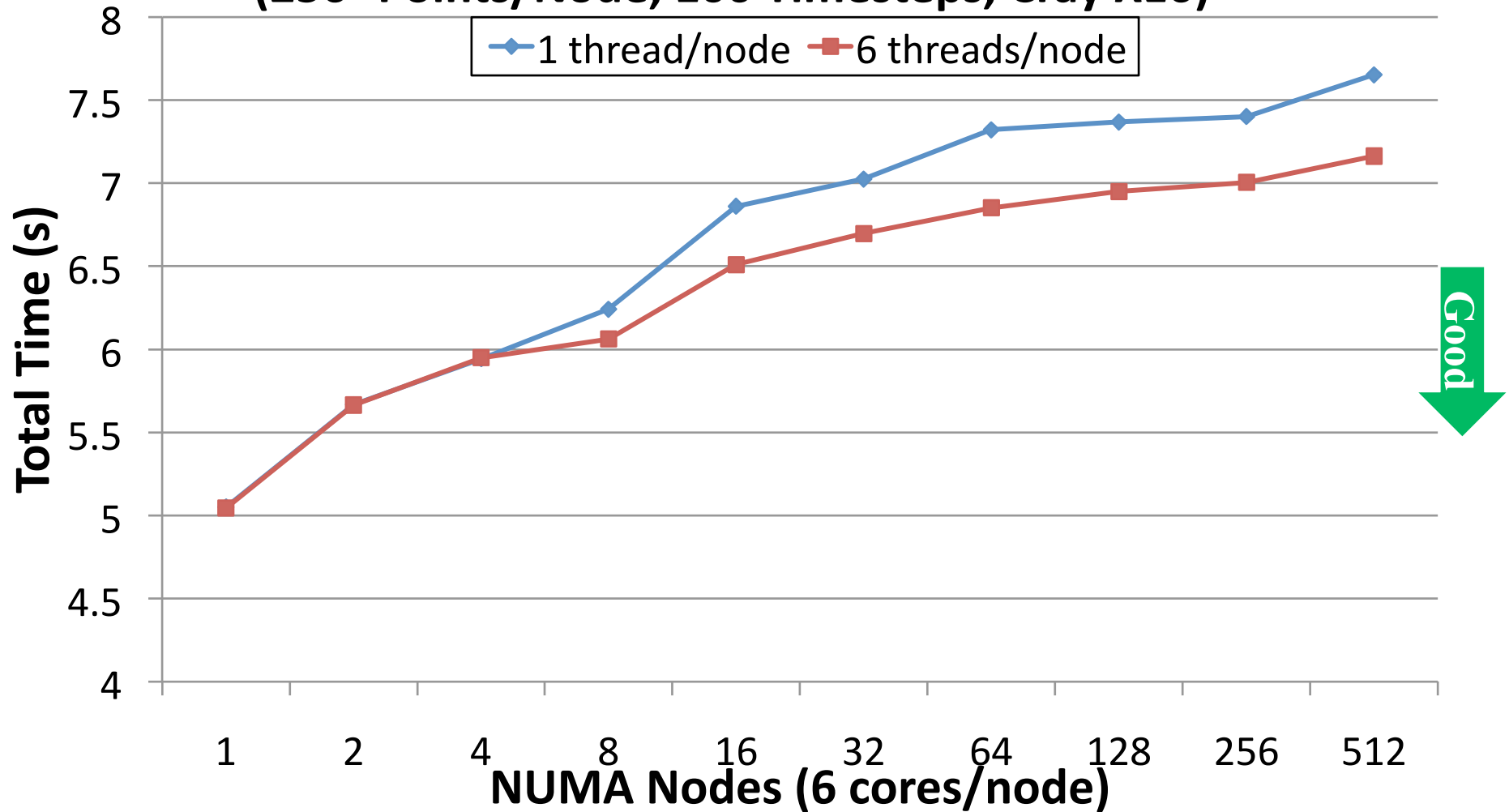
(10,000,000 elements/core, 10,000 samples/core)



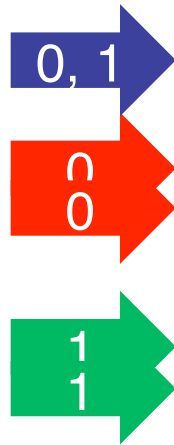
## Sort Communication Concurrency (Cray XE6) (10,000,000 elements/core, 10,000 samples/core)



## Stencil Communication Concurrency (256<sup>3</sup> Points/Node, 100 Timesteps, Cray XE6)



- ❖ Misaligned collective operations can result in deadlock
- ❖ Enforcing textual alignment of collectives at runtime can provide safety and analyzability while minimizing programmer burden
- ❖ Basic idea:
  - Track control flow on all threads
  - Check that preceding control flow matches when:
    - Performing a team collective
    - Changing team contexts
- ❖ Compiler instruments source code to perform tracking and checking



```

5  if (Ti.thisProc() == 0)
6    Ti.barrier();
7  else
8    Ti.barrier();

```

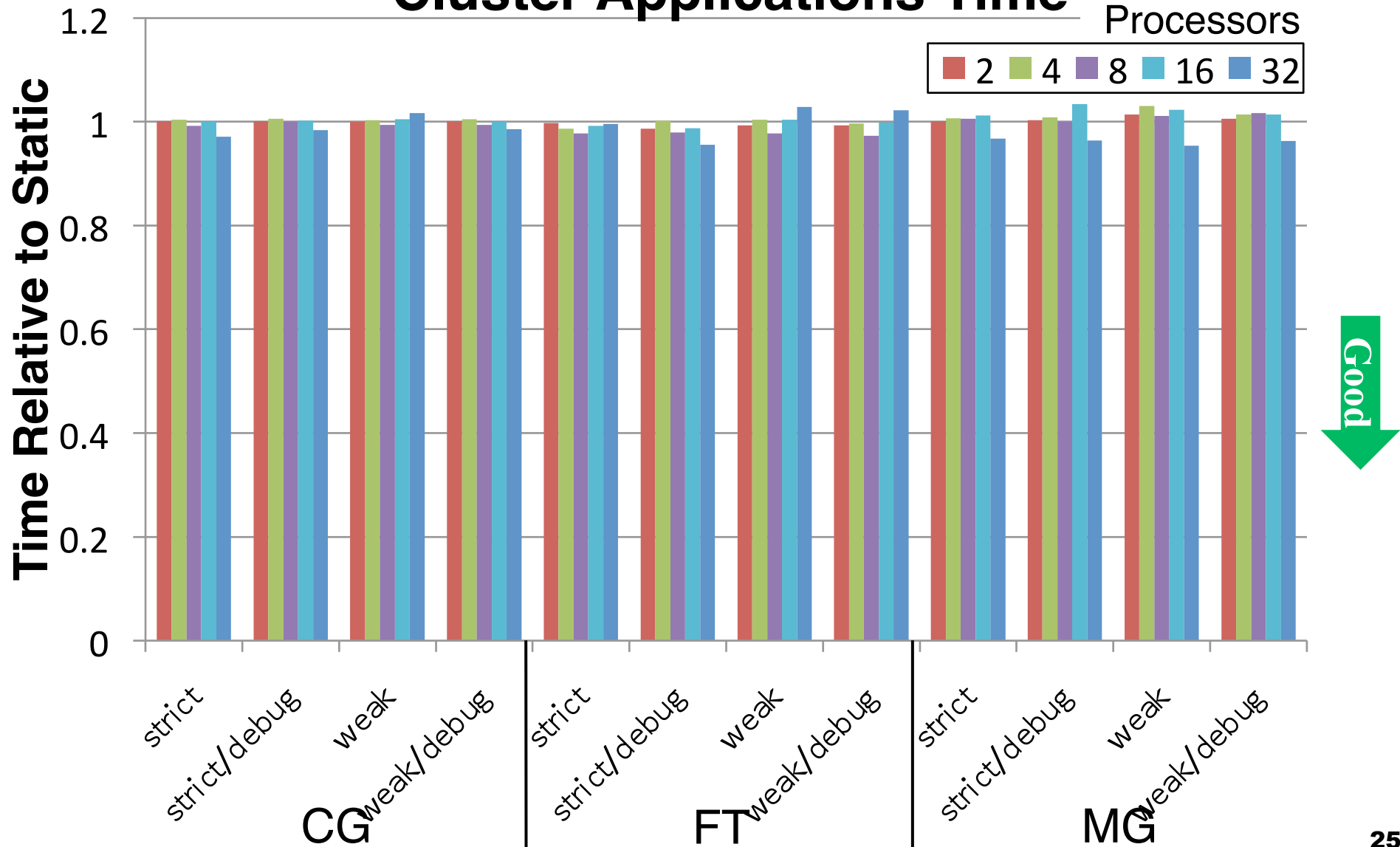
Meaningful error  
generated  
local hash

Thread	Hash	Hash from C	MISALIGNMENT
0	<del>0x00000000</del> 0x7e8a6fa0	0x7e8a6fa0	... * (5, then)
1	0x00027693a	0x7e8a6fa0	... * (5, else)

\* Entries prior to line 5



## Cluster Applications Time



- ❖ Hierarchical language extensions simplify job of programmer
  - Can organize application around machine characteristics
  - Easier to specify algorithmic hierarchy
  - Seamless code composition
  - Better productivity, performance with team collectives
    - See poster for details
- ❖ Language extensions are safe to use
  - Safety provided by lexical scoping and dynamic alignment checking

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